



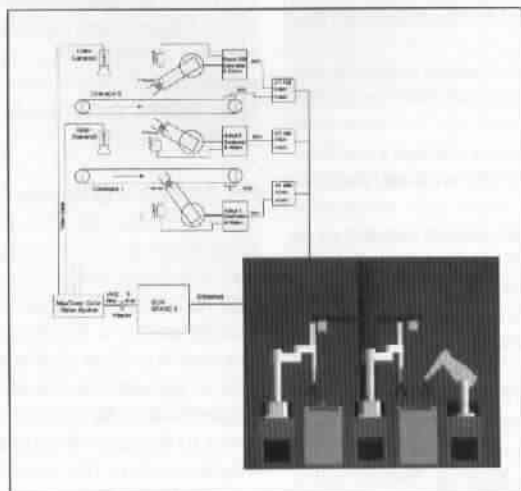
# A Subject-Indexed Bibliography of Discrete Event Dynamic Systems

.....  
A subject-indexed bibliography of Discrete Event Dynamic Systems is given. Each subject is briefly described and some characteristic topics and references for each subject are listed. The complete reference list is provided on the ftp-site and instructions how to retrieve related files are given.  
.....

**T**his paper contains a description of a fairly complete and detailed bibliography of published books, journal, transaction, and conference papers, technical reports and other research publications related to the Discrete Event Dynamic Systems (DEDS) area.

The main objective of the paper is to provide researchers with a comprehensive list of research in DEDS. Moreover, this paper may serve, we hope, as a "look-up table" for literature review purposes, as well as to support the interested researcher in pursuing his/her interest in DEDS and/or in trying to identify new research topics.

The list of references has been divided into subject-indexed areas. Survey and/or general papers may have been listed in more than one subject areas, according to their specific con-



*The University of Southern Louisiana Robotics and Automation Laboratory CIM system, shown in schematic and SILMA simulation, is an example of a DEDS system.*

*Tarek M. Sobh, Jonathan C. Owen (Computer Science Department, 3190 Merrill Engineering Building, University of Utah, Salt Lake City, UT 84112.)  
Kimon P. Valvanis, Denis Gracanin (Robotics and Automation Laboratory, The Center for Advanced Computer Studies and Apparel-CIM Center, The University of Southwestern Louisiana, Lafayette, LA 70504-4330),*

tent. All Petri Net related publications, as applied to CIM, FMS and in general automated manufacturing systems, have been listed separately, mainly due to the fact that Petri Net related research is a rapidly evolving and expanding area.

Each subject-indexed reference represents the state-of-the-art developments in the pertinent area. The authors believe that any finer area distinction will not serve a better purpose. This is left to the individual reader.

Due to the obvious space limitations, only selective references are listed in each of the subject area. The complete list of approximately 1,600 references is available to every reader from the ftp-site which contains the complete BibT<sub>E</sub> file. Instructions related to how to access this file are given in Section 3.

It is very important to emphasize that a comprehensive list of written books is included in this paper, while the representative 170 references, explicitly cited at the end of the paper, represent only a "flavor" of the voluminous work reported in the literature and is by no means complete.

To facilitate reading the paper, brief descriptions of reported work are presented in each subject-indexed section.

Finally, this work is part of the Discrete Event Systems Technical Activity Committee of the IEEE Robotics and Automation Society. The Committee's goal is to provide an annual, updated comprehensive list of references in DEDS, thus creating a dynamic database available to everyone through the ftp-site.

## SUBJECT INDEX

For each subject-index area a short description and several representative references are given.

## A LIST OF REPRESENTATIVE BOOKS

Good understanding of the DEDS area requires a knowledge of different topics, like control theory, probability, operation research, etc. Several books which provide a good introduction and a coverage of some advanced topics are listed in the sequel: [6], [7], [8], [11], [13], [15], [16], [17], [14], [19], [20], [21], [24], [22], [25], [27], [34], [40], [42], [43], [44], [46], [47], [49], [54], [56], [58], [59], [62], [64], [67], [68], [73], [77], [75], [79], [81], [83], [86], [87], [88], [89], [91], [92], [94], [99], [107], [109], [117], [114], [116], [120], [128], [129], [130], [131], [133], [134], [135], [136], [145], [148], [151], [156], [164], [170].

**Algorithms** This subject includes description of various algorithms applied to DEDS problems, as well as the theory of algorithms in general. Most of these algorithms are related to the problems of scheduling, perturbation analysis, control and queues. Their definitions and a representative reference follows:

**Scheduling:** a sequence of actions is generated to achieve a desired goal [139].

**Perturbation analysis:** a system is analyzed by introducing a small change in the system parameters (perturbation) [76].

**Control:** selecting proper actions to achieve desired system behavior [144], and

**Queues:** study of the stochastic nature of a system [65].

**Applications.** Various theoretical models (Petri Nets, stochastic, perturbation) are applied to particular problems like flexible manufacturing systems [5], resource sharing [35], transportation [111], real-time systems [155], etc. The models are used for analysis, synthesis, control and performance evaluation of a wide variety of DEDS.

**Assembly.** The assembly related references are divided into two main categories:

**Plan generation:** generation of a sequence of actions or to schedule tasks to achieve desired functioning of the system [29], [157], [167], and,

**Error recovery:** recovery from errors during the execution of a plan [85], [104].

A recently developed approach is based on the concept of "reverse assembly", widely referenced in recent studies.

**Automation.** This subject is closely related to assembly because the solution process for the problems of the plan gener-

ation and the error recovery involves automatization and generalization, i.e., for a given class of assembly processes a more or less general model (Petri Nets, hierarchical control) is used to automatically create plans and/or error recovery procedures. Representative references include [4], [10], [167], [169].

**Concurrency.** Concurrency includes coordination, control and error recovery of a set of concurrently competing processes. Real-time constraints, temporal semantics, resource sharing are some of the problems to be solved. Analysis, performance evaluation and verification of concurrent systems provide a way to measure the quality of the control process. Concurrency is not limited to the assembly and manufacturing systems, but it is also used in databases, distributed systems, protocols, etc. [93], [109], [122], [152].

**Control.** Various theoretical and practical aspects of the control of DEDS, like stability, robustness, controllability, etc. have been explored. This subject has the most references, due to the fact that the control is crucial to the system theory and therefore to DEDS [25], [46], [69], [91], [102], [108], [124], [161].

**Hierarchical Control.** Hierarchical control utilizes the structure of hierarchical, multilevel systems, and provides a more efficient way to control automated manufacturing systems by studying parts of the system at different level of abstraction, detail, and organizing the sequence of tasks to be executed in a hierarchical way [41], [74], [118], [165], [168].

**Manufacturing.** Manufacturing overlaps heavily with scheduling, automation and robotics. Various theoretical results are applied to this specific class of applications, e.g. design, analysis, performance evaluation, etc. [4], [32], [55], [78], [92], [127], [140], [154].

**Markov Chains.** The memoryless property of many real-time DEDS processes enables the application of Markov chains as a powerful tool for analysis. Various simulations, numerical methods, sensitivity analysis are applied to determine properties of the modeled DEDS [86], [130], [146], [159], [166].

**Observers.** As a part of sensitivity analysis and constructibility, observability is an important property of any DEDS. Observability is considered both during the design and implementation phase of a system [101], [125], [142], [150].

**Operations Research.** Methods of operation research are integrated with the system theory to provide solutions for problems like queueing networks, scheduling, etc. [2], [66], [70].

**Perturbation Systems.** Research reported in this area follows theoretical developments in perturbation analysis [31], [38], [62], [72], [143], [153].

**Petri Nets.** Petri Net models are extensively used in the modeling of DEDS. This includes ordinary Petri Nets, restricted Petri Nets, timed Petri Nets and high-level Petri Nets models. They provide a model for a very general DEDS. Properties of Petri Nets are used to determine or verify properties of the modeled system. Petri Nets and their modifications provide a very powerful mathematical and graphical tool for the study and evaluation of a wide class of systems. [1], [42], [51], [81], [82], [110], [170].

**Queues.** As a part of probability and queueing theory, queues are used to model discrete processes of stochastic nature. Potentially complex networks of queues can be analyzed

either by simulation or by analytical methods. Since a simulation approach is not always feasible, different exact or approximate analytical methods are developed. These include decomposition, aggregation/disaggregation, etc. Parametric and sensitivity analysis is needed to test the quality of a solution [9], [30], [57], [63], [162].

**Real-time Systems.** Real-time constraints imposed on these systems mean that for every DEDS process, there are deadlines that need to be fulfilled. To meet these deadlines, coordination, scheduling, resource management and control must be well implemented. Temporal logic, fault-tolerance and the synchronous approach to reactive systems are some of the ways related to how to model real-time systems. Real-time programming is addressed because it differs significantly from the standard programming style [18], [39], [90], [137], [145].

**Robotics.** Robotics is applied to assembly and autonomous control systems. Multisensor fusion is an important prerequisite for successful use of robots. Remote manipulation, tracking and task-sequencing planning are some of the problems involved. Error recovery is necessary to build an autonomous robot [4], [37], [136], [158], [167].

**Scheduling.** Various approaches to the scheduling problem are discussed, including linear programming, Petri Nets, Lagrange relaxation, and heuristics. Scheduling problems are studied in the context of manufacturing systems, real-time systems, fault-tolerance and job-shop scheduling [2], [33], [53], [100], [119], [160].

**Simulation.** Simulation is a process through which a system model is evaluated numerically, and the data from this process are used to estimate various quantities of interest. Several simulation methods (Monte Carlo, regenerative, discrete-time) and simulation programming languages (GPSS, SIMSCRIPT II.5) are applied to various problems, such as manufacturing scheduling problem, queues, and Markov chains. Sensitivity analysis, accuracy and performance continuity is also explored [13], [36], [61], [97], [132].

**State Machines.** Different models of (finite) state machines are applied to various problems. Control of DEDS is modeled as a hierarchical state machine. A temporal logic is introduced in the state machine and such extended state machine is used for system specification and modeling [23], [112], [163].

**State Space.** The state of the system at a time instant  $t$  represents a (measurable) behavior of the system. The set of all possible values that the state may take, the state space, is in the general case very large. Problems of estimating the state-space size and developing new approaches to reduce the state-space or to deal with its complexity are described here [60], [113], [158].

**Supervisors.** Supervisors and supervisory controls refer to the form of control which involves enabling/disabling actions in a system. Such control involves predictability, lookahead policies, languages generated by the control process, modularity, Petri Nets models, etc. [103], [126], [147], [149].

**Survey Papers.** Although the authors are not aware of a survey paper which covers the whole DEDS area, several survey papers cover some of the subjects, including Petri Nets, perturbation analysis, control architectures, scheduling theory, and queueing networks [3], [12], [28], [45], [48], [50], [52], [71], [80], [84], [95], [96], [98], [105], [106], [121], [123],

[141].

**Theory.** A good knowledge of topics related to the DEDS area, like control theory, probability, etc., requires a good knowledge of the related theory. This is especially true for system theory (control, hierarchical control, observers, supervisors), probability (Markov chains, queues, simulation), automata theory, etc. Selected papers and books provide a good introduction and as well as coverage of advance level topics [26], [79], [107], [115], [120], [138].

## HOW TO OBTAIN THE COMPLETE REFERENCE LIST

All references listed here can be reached by using ftp. The ftp-site is [ftp.cacs.usl.edu](ftp:cacs.usl.edu) and the references are stored in the directory **pub/deds** in the file **deds.bib** (BIET<sub>E</sub>X format). In addition, for each subsection in Section 2, there are three related files which contain selected references, one in BIET<sub>E</sub>X format, one in PostScript format, and one containing **\cite** commands to be used together with **deds.bib**. In addition, a L<sup>A</sup>T<sub>E</sub>X file used to generate a PostScript file is provided. References which don't fit well in a single category are also listed. The **README** file contains information about all bibliography related files and how to use them.

An example of the ftp-session follows:

```
% ftp ftp.cacs.usl.edu
Connected to basin.cacs.usl.edu.
220 basin.cacs.usl.edu FTP server...
Name (basin.cacs.usl.edu: user): anonymous
331 Guest login ok, send ident as password.
Password:
230 Guest login ok, access restrictions apply.
ftp> cd pub/deds
250 CWD command successful.
ftp> get deds.bib
200 PORT command successful.
150 ASCII data connection for deds.bib ...
226 ASCII Transfer complete.
local: deds.bib remote: deds.bib
411339 bytes received ...
ftp> quit
221 Goodbye
```

If only a particular topic is needed, e.g., Petri Nets, selected references can be retrieved by getting the following files:

**petri.bib** A list of selected references in the BIET<sub>E</sub>X format,  
**petri.ps** A list of selected references in Postscript format,  
**petri.cite** A list of indexes of selected references (ocite commands), and,  
**petri.tex** A L<sup>A</sup>T<sub>E</sub>X file used to generate **petri.ps**.

Therefore, for any of the subject areas, the related files are **area.bib**, **area.ps**, **area.cite**, and **area.tex**.

## CONCLUSION

The major objective of this subject-indexed bibliography paper has been to summarize and group most research publications in the area of DEDS. As a result of this effort, it is believed that, through this extensive list, the present research di-



rections related to several issues (modeling, synthesis, analysis, control, simulation, performance evaluation) of DEDS, will become more evident and clear. The reader will be able to isolated the most promising techniques related to the study of a specific aspect of an automated manufacturing system, or even define new directions in research.

The authors' wish is to serve continuously the professional community by providing on an annual basis an updated list of references, thus keeping track of current research and developments in this area.

## REFERENCES

- [1] T. Agerwala, "Putting Petri nets to work," in *Modeling and Control of Automated Manufacturing Systems* (A. A. Desrochers, ed.), Washington, D. C.: IEEE Computer Society Press, 1990.
- [2] R. Akella, O. Maimon, and S. Gershwin, "Value function approximation via linear programming for FMS scheduling," *International Journal of Production Research*, vol. 28, no. 8, pp. 1459-1470, 1990.
- [3] R. Y. Al-Jaar and A. A. Desrochers, "A survey of Petri nets in flexible manufacturing systems," in *Proceedings of 1988 IMACS Conf.*, July 1988.
- [4] R. Y. Al-Jaar and A. A. Desrochers, *Advances in automation and robotics*, vol. 2, ch. Petri nets in automation and manufacturing, pp. 153-225. JAI Press, 1990.
- [5] H. Alla, P. Ladet, J. Martinez, and M. Silva, "Modeling and validation of complex systems by colored Petri nets application to a flexible manufacturing system," in *Advances in Petri Nets 1984*, vol. 188 of *Lecture Notes in Computer Science*, pp. 15-31, Berlin: Springer-Verlag, 1984.
- [6] P. J. Antsaklis and K. M. Passino, eds., *An Introduction to Intelligent and Autonomous Control*. Boston: Kluwer Academic Publishers, 1993.
- [7] F. Baccelli, G. Cohen, G. J. Olsder, and J. P. Quadrat, *Algebraic and stochastic analysis of timed discrete event systems*. Wiley, 1991.
- [8] F. Baccelli, G. Cohen, G. J. Olsder, and J. P. Quadrat, *Synchronization and Linearity*. Wiley, 1992.
- [9] F. Baccelli and Z. Liu, "On the execution of parallel computations on multiprocessor systems—a queueing theory approach," *Journal of the ACM*, vol. 27, no. 32, pp. 373-414, 1990.
- [10] A. D. Baker, T. L. Johnson, D. I. Kerpelman, and H. A. Sutherland, "GRAFCEP and SFC as factory automation standards," in *Proceedings of 1987 American Control Conference*, (Minneapolis, MN), pp. 1725-1730, June 1987.
- [11] K. Baker, *Introduction to sequencing and scheduling*. Wiley, 1974.
- [12] A. Ballakur and H. Steudel, "Integration of job shop control systems: A state-of-the-art review," *Journal of Manufacturing Systems*, vol. 3, no. 1, pp. 71-80, 1984.
- [13] J. Banks and J. S. Carson, *Discrete-Event System Simulation*. Englewood Cliffs, NJ: Prentice-Hall, 1984.
- [14] D. D. Bedworth, M. R. Henderson, and P. M. Wolfe, *Computer-Integrated Design and Manufacturing*. McGraw-Hill, 1991.
- [15] R. Bellman and S. Dreyfus, *Applied dynamic programming*. Princeton, NJ: Princeton Univ. Press, 1962.
- [16] M. Ben-Ari, *Principles of concurrent programming*. Prentice-Hall, 1982.
- [17] S. Bennett, *Real-time computer control: an introduction*. Englewood Cliffs, NJ: Prentice-Hall, 1988.
- [18] A. Benveniste, P. Le Guernic, and C. Jacquemot, "The SIGNAL software environment for real-time system specification, design, and implementation," in *Proceedings of 1989 IEEE Work. CACSD*, Dec. 1989.
- [19] J. Billingsley, *Controlling with computers: control theory and practical digital systems*. McGraw-Hill, 1989.
- [20] J. T. Black, *The Design of the Factory with a Future*. McGraw-Hill, 1991.
- [21] G. V. Bochmann, *Distributed System Design*. Springer-Verlag, 1983.
- [22] P. Bratley, B. Fox, and L. Schrage, *A Guide to Simulation*. New York: Springer-Verlag, 2nd ed., 1987.

- [23] Y. Brave and M. Heymann, "Control of discrete event systems modeled as hierarchical state machines," Tech. Rep. #9012, Center for Intelligent Systems, Technion - Israel Institute of Technology, Haifa, Israel, Mar. 1991.
- [24] P. Brémaud, *Point Processes and Queues—A Martingale approach*. Springer-Verlag Series in Statistics, New York: Springer-Verlag, 1981.
- [25] W. L. Brogan, *Modern Control Theory*. Englewood Cliffs, NJ: Prentice-Hall, 3rd ed., 1991.
- [26] S. D. Brookes, C. A. R. Hoare, and A. W. Roscoe, "A theory of communicating sequential processes," *Journal of the ACM*, vol. 31, no. 3, pp. 560-599, 1984.
- [27] A. Burns and A. Wellings, *Real-Time Systems and Their Programming Languages*. Addison-Wesley, 1990.
- [28] J. A. Buzacott and D. D. Yao, "Flexible manufacturing systems: a review of analytical models," *Management Science*.
- [29] T. Cao and A. C. Sanderson, "Task decomposition and analysis of assembly sequence plans using Petri nets," in *Proceedings of 3rd Int. Conf. CIM*, pp. 138-147, May 1992.
- [30] X.-R. Cao, "On a sample performance function of Jackson queueing networks," *Operations Research*, vol. 36, pp. 128-136, 1988.
- [31] X.-R. Cao and Y. Dallery, "An operational approach to perturbation analysis of closed queueing networks," in *Proceedings of 1986 American Control Conference*, 1986.
- [32] C. G. Cassandras, "Optimizing recirculation in flexible manufacturing systems," in *Proceedings of 2nd ORSA/TIMS Conf. Flexible Manufacturing Systems: Operations Research Models and Applications* (K. E. Stecke and R. Suri, eds.), pp. 381-392, Elsevier, 1986.
- [33] C. G. Cassandras, "On the duality between routing and scheduling systems with finite buffer space," in *Proceedings of 31st IEEE Conference on Decision and Control*, pp. 2364-2365, Dec. 1992.
- [34] C. G. Cassandras, *Discrete Event Systems: Modeling and Performance Analysis*. The Aksen Associates Series in Electrical and Computer Engineering, Homewood, IL 60430: Aksen Associates Incorporated Publishers, 1993.
- [35] C. G. Cassandras and J. I. Lee, "Applications of perturbation techniques to optimal resource sharing in discrete event systems," in *Proceedings of 1988 American Control Conference*, (Atlanta, GA), pp. 450-455, 1988.
- [36] U. Chandrasekaran and S. Sheppard, "Discrete event distributed simulation—a survey," in *Proceedings of Conference on Methodology and Validation*, pp. 32-37, 1987.
- [37] P. R. Chang, *Parallel Algorithms and VLSI architectures for robotics and assembly scheduling*. PhD thesis, Purdue Univ., West Lafayette, IN, Dec. 1988.
- [38] E. K. P. Chong and P. J. Ramadge, "Convergence of recursive optimization algorithms using IPA derivative estimates," in *Proceedings of 1990 American Control Conference*, (San Diego, CA), May 1990.
- [39] S. Connolly, Y. Dallery, and S. B. Gershwin, "A real-time policy for performing setup changes in a manufacturing system," in *Proceedings of 31st IEEE Conference on Decision and Control*, pp. 764-770, Dec. 1992.
- [40] A. E. Conway and N. D. Georganas, *Queueing Networks—Exact Computational Algorithms: A Unified Theory Based on Decomposition and Aggregation*. Cambridge, MA: The MIT Press, 1989.
- [41] B. Darakanada, "Simulation of manufacturing process under a hierarchical control algorithm," Master's thesis, MIT, May 1989.
- [42] R. David and H. Alla, *Petri Nets and Grafset: Tools for modelling discrete event systems*. New York: Prentice-Hall, 1992.
- [43] E. V. Denardo, *Dynamic Programming: Models and Applications*. Englewood Cliffs, NJ: Prentice-Hall, 1982.
- [44] M. J. Denham and A. J. Laub, eds., *Advanced Computing Concepts and Techniques in Control Engineering*, vol. 47 of *Computer and Systems Sciences*. Springer-Verlag, 1988.
- [45] P. Deransart, M. Jourdan, and B. Lohro, "A survey of attribute grammars part 1: Main result on attribute grammars," Tech. Rep. 485, INRIA, Jan. 1986.
- [46] A. A. Desrochers, *Modeling and Control of Automated Manufacturing*

[47] R. L. Devaney, *An Introduction to Chaotic Dynamical Systems*. Menlo Park, California: The Benjamin/Cummings Publishing Company, Inc., 1986.

[48] D. Dilts, N. Boyd, and H. Whorins, "The evolution of control architectures for automated manufacturing," *Journal of Manufacturing Systems*, vol. 10, no. 1, pp. 79-93, 1991.

[49] B. R. Donald, *Error Detection and Recovery in Robotics*, vol. 336 of *Lecture Notes in Computer Science*. Berlin: Springer-Verlag, 1989.

[50] S. Drees et al., *Advances in Petri Nets 1987*, ch. Bibliography of Petri nets, pp. 309-341. Springer-Verlag, 1987.

[51] D. Dubois and K. E. Stecke, "Using Petri nets to represent production processes," in *Proceedings of 22nd IEEE Conference on Decision and Control*, (San Antonio, TX), pp. 1062-1067, Dec. 1983.

[52] C. Dupont-Gatelmand, "A survey of flexible manufacturing systems," *Journal of Manufacturing Systems*, vol. 1, no. 1, pp. 1-16, 1982.

[53] S. E. Elmaghraby, "The economic lot scheduling problem (ELSP): Review and extensions," *Management Science*, vol. 24, pp. 587-598, 1978.

[54] M. Elzas, R. I. Oren, and B. Zeigler, eds., *Modelling an simulation methodology in the artificial intelligence era*. Amsterdam: North-Holland, 1986.

[55] W. Eversheim and P. Herrmann, "Recent trends in flexible automated manufacturing," *Journal of Manufacturing Systems*, vol. 1, no. 2, pp. 139-148, 1982.

[56] A. F. Famili, D. S. Nau, and S. H. Kim, eds., *Artificial Intelligence Applications in Manufacturing*. Menlo Park, California: AAAI Press / The MIT Press, 1992.

[57] W. Feller, *An Introduction to Probability Theory and Its Applications*. New York: Wiley, 2nd ed., 1971.

[58] G. S. Fishman, *Principles of Discrete Event Simulation*. New York: John Wiley, 1987.

[59] M. R. Garey and D. S. Johnson, *Computers and Intractability: A Guide to NP-Completeness*. San Francisco, CA: Freeman, 1979.

[60] V. K. Garg and R. Kumar, "A state-variable approach for controlling discrete event systems with infinite states," in *Proceedings of 1992 American Control Conference*, (Chicago, IL), June 1992.

[61] P. Glasserman, "Derivative estimates from simulation of continuous time Markov chains," tech. rep., AT&T Bell Labs, Holmdel, NJ, 1989.

[62] P. Glasserman, *Gradient Estimation via Perturbation Analysis*. Boston: Kluwer Academic Publishers, 1991.

[63] P. Glasserman and Y. C. Ho, "Aggregation approximation for sensitivity analysis of multi-class queueing networks," *Performance Analysis*, vol. 10, pp. 295-308, 1989.

[64] M. Gondran and M. Minoux, *Graphs and algorithms*. New York: Wiley, 1986.

[65] W. B. Gong, W. Zhai, and Y. C. Ho, "Stochastic comparison algorithm for discrete optimization with Monte Carlo estimation," in *Proceedings of 31st IEEE Conference on Decision and Control*, pp. 795-802, Dec. 1992.

[66] G. Gordon, *Handbook of operations research*, ch. Simulation-computation. New York: Van Nostrand, 1978.

[67] M. A. Harrison, *Introduction to Switching and Automata Theory*. New York: McGraw-Hill, 1965.

[68] F. S. Hiller and G. J. Lieberman, *Introduction to Operations Research*. Hopden-Day, 4th ed., 1986.

[69] Y. C. Ho, "Adaptive design of feedback controllers for stochastic systems," *IEEE Transactions on Automatic Control*, vol. 10, pp. 367-368, July 1965.

[70] Y. C. Ho, "System theory and operations research - a new fusion of mathematical modeling and experimentation," in *Proceedings of Workshop on Intelligent Control 1985* (A. Saridis and A. Meystel, eds.), (Troy, NY), pp. 35-37, Aug. 1985.

[71] Y. C. Ho, *A Selected and Annotated Bibliography on Perturbation Analysis*, vol. 106 of *Lecture Notes in Control and Information Science*, pp. 217-224. Berlin: Springer-Verlag, Aug. 1987.

[72] Y. C. Ho, "Recent developments in perturbation analysis," Tech. Rep. CICS-P-209, CICS, Brown Univ., Providence, Apr. 1990.

[73] Y. C. Ho, ed., *Discrete Event Dynamic Systems: Analyzing Complexity and Performance in the Modern World*. New York: IEEE Press, 1991.

[74] Y. C. Ho, "Hierarchical production controls in a stochastic two-machine flowshop with a finite internal buffer," in *Proceedings of 31st IEEE Conference on Decision and Control*, pp. 2068-2073, Dec. 1992.

[75] Y. C. Ho and X.-R. Cao, *Perturbation Analysis of Discrete Event Dynamic Systems*. Boston: Kluwer Academic Publishers, 1991.

[76] Y. C. Ho and J. Q. Hu, "An infinitesimal perturbation analysis algorithm for a multiclass G/G/1 queue," *Operations Research Letters*, vol. 9, pp. 35-44, 1990.

[77] C. A. R. Hoare, *Communicating Sequential Processes*. International Series in Computer Science, Englewood Cliffs, NJ: Prentice-Hall International, 1985.

[78] G. Hoffmann, *Discrete Event System Theory Applied to Manufacturing*. PhD thesis, Stanford, Information Systems Laboratory, Stanford University, CA, Dec. 1992.

[79] J. E. Hopcroft and J. D. Ullman, *Introduction to Automata Theory, Languages and Computation*. Addison-Wesley Series in Computer Science, Reading, Massachusetts: Addison-Wesley, 1979.

[80] R. Hull and R. King, "Semantic database modeling: survey, applications, and research issues," *ACM Computing Surveys*, vol. 19, no. 3, pp. 201-260, 1987.

[81] K. Jensen, *Coloured Petri Nets: A High Level Language for System Design and Analysis*. Berlin: Springer-Verlag, 1991.

[82] K. Jensen, ed., *Application and Theory of Petri Nets 1992*, vol. 616 of *Lecture Notes in Computer Science*. Berlin: Springer-Verlag, 1992.

[83] K. Jensen and G. Rozenberg, eds., *High-level Petri Nets: Theory and Applications*. Berlin: Springer-Verlag, 1991.

[84] B. Jiang, J. Black, and R. Duraisamy, "A review of recent developments in robot metrology," *Journal of Manufacturing Systems*, vol. 7, no. 4, pp. 339-357, 1988.

[85] J.-F. Kao and J. L. Sanders, "Impact of error recovery on the productivity of a unitary assembly cell," *IEEE Transactions on Robotics and Automation*, vol. 8, no. 6, pp. 730-740, 1992.

[86] J. Keilson, *Markov chain models - rarity and exponentiality*. Springer-Verlag, 1979.

[87] L. Kleinrock, *Queueing Systems*, vol. I: Theory. New York: Wiley, 1975.

[88] H. E. Koenig, Y. Tokad, and H. K. Kesavan, *Analysis of Discrete Physical Systems*. New York: McGraw-Hill, 1967.

[89] Z. Kohavi, *Switching and Finite Automata Theory*. McGraw-Hill, 1979.

[90] P. Kozák, "Methods of discrete event systems theory in AI real-time skills," in *Proceedings of the IFIP Workshop on Dependability of Artificial Intelligence Systems DAISY-91* (G. H. Schildt and J. Retti, eds.), (Vienna, Austria), pp. 271-277, Elsevier, North-Holland, Amsterdam, May 1991.

[91] P. R. Kumar and P. Varaiya, *Stochastic Systems: Estimation, Identification, and Adaptive Control*. Englewood Cliffs, NJ: Prentice-Hall, 1986.

[92] A. Kusiak, ed., *Intelligent Design and Manufacturing*. New York: Wiley, 1992.

[93] S. LaFortune and E. Wong, "A state model for the concurrency control problem in database management systems," in *Proceedings of 24th IEEE Conference on Decision and Control*, (Fort Lauderdale, FL), pp. 441-442, Dec. 1985.

[94] A. M. Law and W. D. Kelton, *Simulation Modeling and Analysis*. McGraw-Hill series in industrial engineering and management science. New York: McGraw-Hill, 2nd ed., 1991.

[95] C. Lee, "Fuzzy logic in control systems: fuzzy logic controller - part I," *IEEE Transactions on Systems, Man and Cybernetics*, vol. 20, no. 2, pp. 404-418, 1990.

[96] C. Lee, "Fuzzy logic in control systems: fuzzy logic controller - part II," *IEEE Transactions on Systems, Man and Cybernetics*, vol. 20, no. 2, pp. 419-435, 1990.

[97] A. M. C. Leeming, "A comparison of some discrete event simulation languages," *Simuletter*, vol. 12, no. 1-4, pp. 9-16, 1981.

- [98] J. R. Lenstra and A. H. G. R. Kan, "Scheduling theory since 1981: an annotated bibliography," Tech. Rep. 188/83, Mathematisch Centrum, Amsterdam, 1983.
- [99] S.-T. Levi and A. K. Agrawala, *Real-Time System Design*. New York: McGraw-Hill, 1990.
- [100] A. L. Liestman and R. H. Campbell, "A fault-tolerant scheduling problem," *IEEE Transactions on Software Engineering*, vol. 12, no. 11, pp. 1089-1095, 1986.
- [101] F. Lin, *On Controllability and Observability of Discrete Event Systems*. PhD thesis, University of Toronto, Canada, 1987.
- [102] F. Lin, "Robust and adaptive supervisory control of discrete event systems," in *Proceedings of 1992 American Control Conference*, (Chicago, IL), pp. 2804-2808, June 1992.
- [103] F. Lin and W. M. Wonham, "Decentralized supervisory control of discrete-event systems," Tech. Rep. # 8612, Systems Control Group, Department of Electrical Engineering, University of Toronto, Canada, 1986.
- [104] E. Lopez-Mellado and R. Alami, "A failure recovery scheme for assembly workcells," in *Proceedings of 1990 International Conference on Robotics and Automation*, pp. 702-707, 1990.
- [105] J. M. Maciejowski, "Data structures and software tools for computer aided design of control systems: a survey," in *IFAC Workshop on CACSD*, 1989.
- [106] G. Margirier, "Flexible automated machining in France: Results of a survey," *Journal of Manufacturing Systems*, vol. 6, no. 4, pp. 253-265, 1987.
- [107] M. D. Mesarovic, D. Macko, and Y. Takahara, *Theory of Hierarchical, Multilevel, Systems*. New York: Academic Press, 1970.
- [108] G. Meyer, "On hybrid problems in flight control," in *Workshop on Hybrid Systems*, (Cornell Univ.), MSI, June 1991.
- [109] R. Milner, *Communication and Concurrency*. New York: Prentice-Hall, 1989.
- [110] T. Murata, "Petri nets: Properties, analysis, and applications," *Proceedings of the IEEE*, vol. 77, no. 4, pp. 541-580, 1989.
- [111] G. J. Olsder, "Applications of the theory of discrete event systems to array processors and scheduling in public transportation," in *Proceedings of 28th IEEE Conference on Decision and Control*, Dec. 1989.
- [112] J. S. Ostroff, "Real-time computer control of discrete systems modelled by extended state machines: A temporal logic approach," Tech. Rep. # 8618, Systems Control Group, Department of Electrical Engineering, University of Toronto, Canada, 1986.
- [113] C. M. Özveren, *Analysis and Control of Discrete Event Dynamic Systems: A State Space Approach*. PhD thesis, LIDS, MIT, Cambridge, MA, 1989.
- [114] C. H. Papadimitriou, *Elements of the Theory of Computation*. Englewood Cliffs, NJ: Prentice-Hall, 1981.
- [115] C. H. Papadimitriou, *The Theory of Database Concurrency Control*. Rockville, MD: Computer Science Press, 1986.
- [116] C. H. Papadimitriou and K. Steiglitz, *Combinatorial Optimization: Algorithms and Complexity*. Englewood Cliffs, NJ: Prentice-Hall, 1982.
- [117] A. Papoulis, *Probability, Random Variables and Stochastic Processes*. New York: McGraw-Hill, 3rd ed., 1991.
- [118] K. M. Passino and P. J. Antsaklis, "Event rates and aggregation in hierarchical systems," *Discrete Event Dynamic Systems: Theory and Applications*, vol. 1, no. 3, pp. 271-288, 1991.
- [119] J. R. Perkins and P. R. Kumar, "Stable, distributed, real-time scheduling of flexible manufacturing/assembly/disassembly systems," *IEEE Transactions on Automatic Control*, vol. 34, no. 2, pp. 139-148, 1989.
- [120] J. L. Peterson, *Petri Net Theory and the Modeling of Systems*. Englewood Cliffs, NJ: Prentice-Hall, 1981.
- [121] H. Plüneck and W. Reisig, "Bibliography of Petri nets 1990," in *Advances in Petri Nets 1991* (G. Rozenberg, ed.), vol. 524 of *Lecture Notes in Computer Science*, pp. 317-572, Berlin: Springer-Verlag, June 1991.
- [122] A. Pnueli, "The temporal semantics of concurrent programs," in *Semantics of Concurrent Computations* (G. Kahn, ed.), vol. 70 of *Lecture Notes in Computer Science*, (Berlin), pp. 1-20, Springer-Verlag, 1979.
- [123] A. Pnueli and E. Harel, "Applications of temporal logic to the specification and verification of reactive systems: a survey of current trends," in *Current Trends in Concurrency*, vol. 224 of *Lecture Notes in Computer Science*, (Berlin), pp. 510-584, Springer-Verlag, 1986.
- [124] P. J. Ramadge, *Control and Supervision of Discrete Event Processes*. PhD thesis, University of Toronto, Canada, 1983.
- [125] P. J. Ramadge, "On the periodicity of symbolic observations of piecewise smooth discrete-time systems," *IEEE Transactions on Automatic Control*, vol. 35, no. 7, pp. 807-813, 1990.
- [126] P. J. Ramadge and W. M. Wonham, "Supervision of discrete event processes," in *Proceedings of 21st IEEE Conference on Decision and Control*, (Orlando, FL), pp. 1228-1229, Dec. 1982.
- [127] R. Ravichandran and A. K. Chakravarty, "Decision support in flexible manufacturing systems using timed Petri nets," *Journal of Manufacturing Systems*, vol. 5, no. 2, pp. 89-101, 1986.
- [128] W. Reisig, *A Primer in Petri Net Design*. Berlin: Springer-Verlag, 1992.
- [129] L. C. G. Rogers and D. Williams, *Diffusions, Markov Processes, and Martingales*, vol. 2. New York: Wiley, 1987.
- [130] S. M. Ross, *Introduction to Stochastic Dynamic Programming*. New York: Academic Press, 1983.
- [131] R. Rubinstein, *Monte Carlo Optimization, Simulation, and Sensitivity Analysis of Queueing Networks*. New York: Wiley, 1986.
- [132] R. Rubinstein, "The score function approach of sensitivity analysis of computer simulation models," *Mathematics and Computation in Simulation*, vol. 28, pp. 351-379, 1986.
- [133] S. Rudneanu, *Boolean Functions and Equations*. North-Holland, 1974.
- [134] A. Salomaa, *Theory of Automata*. Oxford, UK: Pergamon Press, 1969.
- [135] B. Sarikaya and G. V. Bochmann, eds., *Protocol Specification, Testing, and Verification*, vol. VI. North-Holland, 1987.
- [136] R. J. Schilling, *Fundamentals of Robotics: Analysis and Control*. Englewood Cliffs, NJ: Prentice-Hall, 1990.
- [137] S. Schneider, *Correctness and communication of real-time systems*. PhD thesis, Oxford Univ., Mar. 1990.
- [138] J. M. Schumacher, "Discrete events: Perspectives from system theory," *CWI Quarterly*, vol. 2, no. 2, pp. 131-146, 1989.
- [139] W. K. Shih, J. W. S. Liu, and J. Y. Chung, "Fast algorithms for scheduling tasks with ready times and deadlines to minimize total error," in *Proceedings of 10th IEEE Real-Time Systems Symp.*, Dec. 1989.
- [140] M. Silva and R. Valette, *Petri Nets in Flexible Manufacturing*, pp. 375-417. Advances in Petri Nets, Berlin: Springer-Verlag, 1990.
- [141] J. L. Snowden and J. C. Ammons, "A survey of queueing network packages for the analysis of manufacturing systems," *Manufacturing Review*, vol. 1, pp. 14-25, 1988.
- [142] T. Sobh, *Active Observer: A Discrete Event Dynamic System Model for Controlling an Observer Under Uncertainty*. PhD thesis, University of Pennsylvania, Philadelphia, PA, Dec. 1991.
- [143] T. Sobh, "Performance evaluation via perturbation analysis," Tech. Rep. 263, GRASP Lab, University of Pennsylvania, Philadelphia, PA, May 1991.
- [144] X. Song and J. W. S. Liu, "Performance of multiversion concurrency control algorithms in maintaining temporal consistency," in *Proceedings of IEEE CompSoc*, (Chicago, IL), Nov. 1990.
- [145] J. A. Stankovic and K. Ramamritham, eds., *Tutorial: Hard Real-Time Systems*. Washington, D. C.: IEEE Computer Society Press, 1988.
- [146] S. G. Strickland and C. G. Cassandras, "An 'augmented chain' approach for on-line sensitivity analysis of Markov processes," in *Proceedings of 26th IEEE Conference on Decision and Control*, (Los Angeles, CA), pp. 1873-1878, Dec. 1987.
- [147] A. Tomlinson, G. Hoagland, and V. K. Garg, "Distributed resource management using active supervisory predicate control," in *Proceedings of 1992 American Control Conference*, (Chicago, IL), June 1992.
- [148] K. P. Valavanis and G. N. Saridis, *Intelligent Robotic Systems: Theory, Design and Applications*. Boston: Kluwer Academic Publishers, 1992.



- tech. rep., Software Engineering Institute, Carnegie Mellon Univ., Mar. 1989.
- [156] D. S. Weld, *Theories of comparative analysis*. The MIT Press, 1990.
- [157] G. Werling, "Planning of sensing tasks in an assembly environment," *Journal of Intelligent and Robotic Systems*, vol. 4, pp. 221-254, 1991.
- [158] D. E. Whitney, "State space models of remote manipulation tasks," *IEEE Transactions on Automatic Control*, vol. 14, no. 6, pp. 617-623, 1969.
- [159] W. Whitt, "Continuity of generalized semi-Markov processes," *Mathematics of Operations Research*, vol. 5, pp. 494-501, 1980.
- [160] H. Wong-Toi and D. L. Dill, "Synthesizing processes and schedulers from temporal specifications," in *Computer-Aided Verification '90, DI-MACS Series in Discrete Mathematics and Theoretical Computer Science, Volume 3*, pp. 177-186, American Mathematical Society, 1991.
- [161] W. M. Wonham, *Computational and Combinatorial Methods in System Theory*, ch. On Control of Discrete Event Systems, pp. 159-174. North-Holland: Elsevier Science Publisher B.V., 1986.
- [162] C. M. Woodside, "Response time sensitivity measurement for computer systems and general closed queueing networks," *J. Performance Evaluation*, vol. 4, pp. 199-210, 1984.
- [163] Y. T. Yu and M. G. Gouda, "Deadlock detection for a class of communicating finite state machines," *IEEE Transactions on Communications*, vol. 30, no. 12, pp. 2512-2516, 1982.
- [164] B. P. Zeigler, *Multifaceted modelling and discrete event simulation*. New York: Academic Press, 1984.
- [165] B. P. Zeigler, "Hierarchical, modular discrete event modelling in an object oriented environment," *Simulation J.*, vol. 49, no. 5, pp. 219-230, 1987.
- [166] B. Zhang, *Performance gradient estimation for very large Markov chains*. PhD thesis, Harvard Univ., 1990.
- [167] W. Zhang, "Representation of assembly and automatic robot planning by Petri net," *IEEE Transactions on Systems, Man and Cybernetics*, vol. 19, no. 2, pp. 418-422, 1989.
- [168] H. Zhong and W. M. Wonham, "On the consistency of hierarchical supervision in discrete-event systems," *IEEE Transactions on Automatic Control*, vol. 35, no. 10, pp. 1125-1134, 1990.
- [169] M. C. Zhou, *A Theory for the Synthesis and Augmentation of Petri Nets in Automation*. PhD thesis, ECSE, Rensselaer Polytechnic Institute, Troy, NY, 1990.
- [170] M. C. Zhou and F. DiCesare, *Petri Net Synthesis for Discrete Event Control of Manufacturing Systems*. Boston: Kluwer Academic Publishers, 1993.



**Tarek M. Sobh** received the B.Sc. in Engineering degree in Computer Science and Automatic Control from the Faculty of Engineering, Alexandria University, Egypt in 1988, and M.S. and Ph.D. degrees in Computer and Information Science from the General Robotics and Active Sensory Perception (GRASP) laboratory, School of Engineering, University

of Pennsylvania in 1989 and 1991, respectively. He is currently a Research Assistant Professor in the Department of Computer Science, University of Utah. Dr. Sobh is the Co-Chairman of the Discrete Event Dynamic Systems (DEDS) Technical Committee of the IEEE Robotics and Automation Society. The background of Dr. Sobh is in the fields of computer science and engineering, control theory, robotics, computer vision and signal processing. His research interests include reverse engineering and industrial inspection, robot prototyping and robot environments, CAD/CAM and active perception under uncertainty. Professor Sobh is also interested in developing tools for adaptive robotic sensing in unstructured environments.



**Kimon Valavanis** received his Ph.D. from Rensselaer Polytechnic Institute in 1986. Since January, 1991, he has been with The Center for Advanced Computer Studies, The University of Southwestern Louisiana (USL), where he is currently an Associate Professor of Computer Engineering and Associate Director for Research in Robotics and Automation at the USL Apparel-CIM Center.

Dr. Valavanis' research interests are in the area of Robotics and Automation Systems, Intelligent Machines and Automated Manufacturing Systems. He has published over 100 book chapters, technical journal/transactions and conference papers. He is the co-author of the book (with Dr. G. N. Saridis) *Intelligent Robotic System: Theory, Design and Application*, Kluwer Academic Publishers, 1992. He serves as the Robotics and Automation Society Discrete Event Dynamic System Technical Committee Co-Chair, he is an Associate Editor of the *IEEE Robotic and Automation Society Magazine*, and he is the Book Reviewer. Dr. Valavanis is a Senior member of IEEE, a member of Sigma Xi, a member of the Academy of Sciences of New York, ISRA and RIA.



**Denis Gracanin** was born in Rijeka, Croatia, in 1963. He received the B.Sc. and M.Sc. degrees in Electrical Engineering from the University of Zagreb, Croatia, in 1985 and 1988, respectively. He also received the M.Sc. and Ph.D. degrees in Computer Science from the University of Southwestern Louisiana, Lafayette, LA in 1992 and 1994, respectively.

Between 1985 and 1991 he was a lecturer assistant at the Telecommunications Department, University of Zagreb, Croatia. He currently holds a postdoctoral position at the Apparel-CIM Center, University of Southwestern Louisiana, Lafayette, LA. His research interests are in the field of Petri nets, intelligent robotic systems and automated manufacturing systems. Dr. Gracanin is a member of IEEE, ACM, AAAI and SIAM.



**Jonathan Owen** received a B.S. in mechanical engineering in 1986 from Rice University. He was employed by the McDonnell-Douglas Corporation as an engineer in its Structural Research Department in St. Louis until 1989. Some of the projects he worked on included development and support of a pre- and post-processor for finite element analysis and heat exchanger design for the National Aerospace Plane (NASP). He then worked with Noetic Technologies and later the MacNeal-Schwendler Corporation as a software engineer, developing P-version finite element interfaces. In 1991, Mr. Owen entered the graduate program in computer science at the University of Utah. He has since concentrated on computer vision and is currently working on his thesis, "Feature-based Reverse Engineering".